

## 31. COPx-AX4 (Motor Output Stage for 4 Axes)

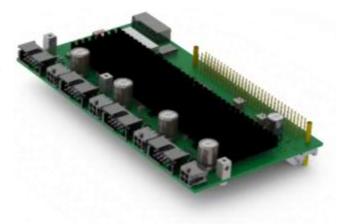
COPx-AX4

611653900

COPx is a COP card in a larger format with dimension 150 x 80mm. This module was specially developed for applications directly on a machine head periphery. Currently only permanent magnet synchronous motors (BLDC or EC) are supported. Only incremental encoders can be used as feedback system. In addition, an integrated braking resistor is available.



For the motor control, a COP-MAS or COP-MAS2 module with a free processor core is needed in the same COP case. Only a maximum of three COPx-AX4 modules can be used per COP node.





If a COP node contains COPx-AX4 modules, they must start with the rotary switch address 0. Further COPx-AX4 modules follow with increasing addressing. This means when using one module the address is set to 0. When using three modules, the addresses are set to 0, 1 and 2. All other COPx/COP module types begin at address 3 and following.



If an external motor brake is additionally connected or if the motor has Hall sensors, a COPx-ADIO or COP-IO module is required in the same COP node. Hall sensors must be connected to the ascending numbered digital inputs. For example: Hall 1 at DIN 1, Hall 2 at DIN 2 and Hall 3 at DIN 3.

### 31.1. Technical Specifications

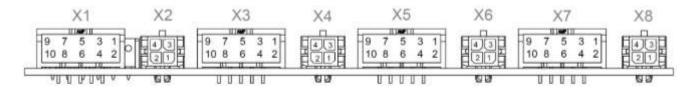
Motor Output Stage				
Number of output stages	4			
Integrated braking resistor	56Ω/5W			
Rated intermediate circuit voltage	48	V <sub>DC</sub>		
Maximum intermediate circuit power supply	56	V <sub>DC</sub>		
Continuous current per final stage	2.5	A <sub>RMS</sub>		
Peak current (Max 5s) per final stage	5	A <sub>RMS</sub>		
Protection	Excessive temperature and over-current			
Connector	Molex 43045-0400			

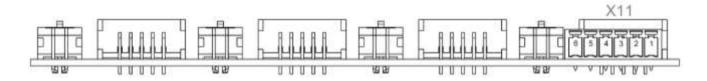


Motor			
Minimum inductance	1	mH	
Minimum resistance	0.2	Ω	
Maximum cable length	20	m	
Motor cable	Shielded		
Types of motor	Three-phase synchronous motors with permanent magnet DC motors		
Incremental Encoder Interface			
Level	RS422		
Input impedance	2.2	kΩ	
Maximum input frequency	2.5	MHz	
Maximum current load at 5V output	200	mA	
Power cable	Unshielded		
Connector	TE Low Pro HDR 10P		
Module			
Maximum power consumption at 24V node power supply	100	mA	



# 31.2. Pin Assignment





X1, X3, X5, X7					
No.	Dir	Id.	ld.	Dir	No.
2	Out	Enc_5V	NC		1
4		NC	GND		3
6	In	Inc A+	Inc A-	In	5
8	In	Inc B+	Inc B-	In	7
10	In	Ref+	Ref-	In	9

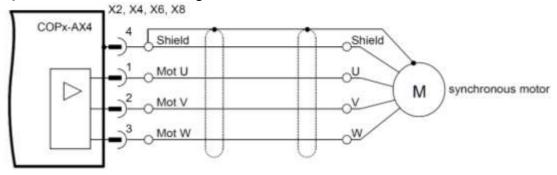
	X2, X4, X6, X8					
No.	No. Dir Id.		Id.	Dir	No.	
2	Out	Mot V	Mot U	Out	1	
4 Shield		Mot W	Out	3		

X11					
No.	Dir	ld.			
1		Earth			
2		Earth			
3		GND			
4		GND			
5	In	Mot_Ucc			
6	In	Mot_Ucc			

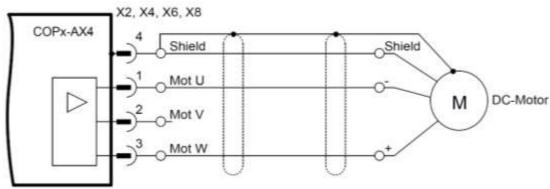


# 31.3. Connection Examples

#### Synchronous motor at a final stage



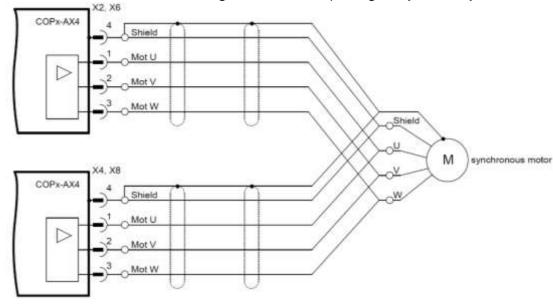
### DC motor at a final stage



#### Synchronous motor at two parallel output stages

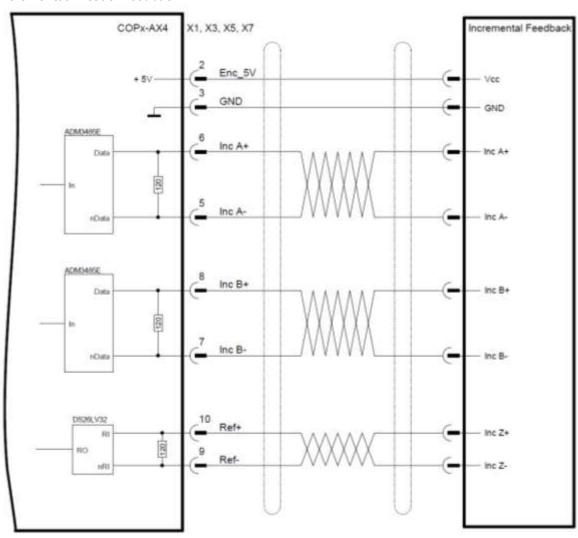


The Y cables must be at least 25cm long, otherwise the output stages may be destroyed.





#### **Incremental Encoder Feedback**



## 31.4. Available Options

Item Number	Label	Option	Description
611653900	COPx-AX4		<ul><li>4x Motor output stage,</li><li>PM, DC motors</li><li>Incremental Encoder Feedback</li></ul>